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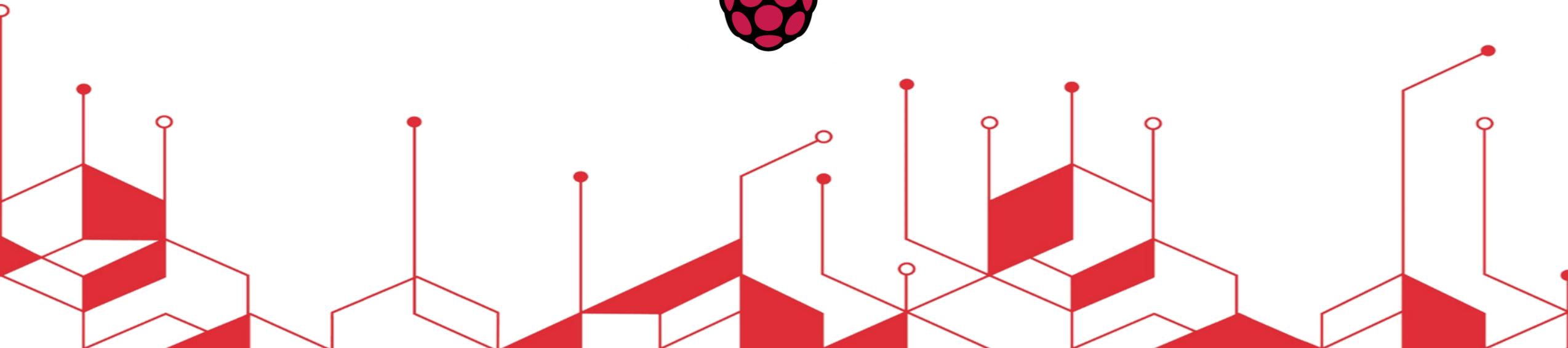
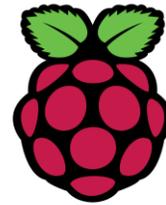


Remote Lab For Engineering Project  
Erasmus+ Program

## Raspberry Pi -Take Home Lab

### Lab Experiment # 5

Analog Output Using Pulse Width Modulation(PWM)

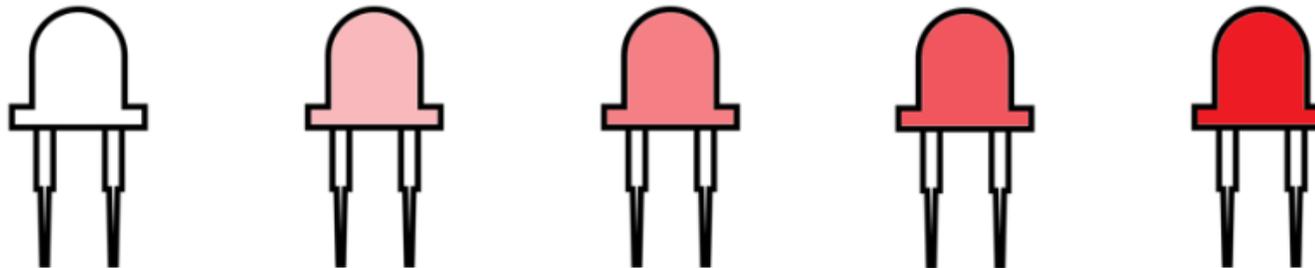


# PWM - Pulse Width Modulation

It is a commonly used control technique that generates analog signals from digital devices such as microcontrollers.

In PWM technique, the signal's energy is distributed through a series of pulses rather than a continuously varying (analog) signal.

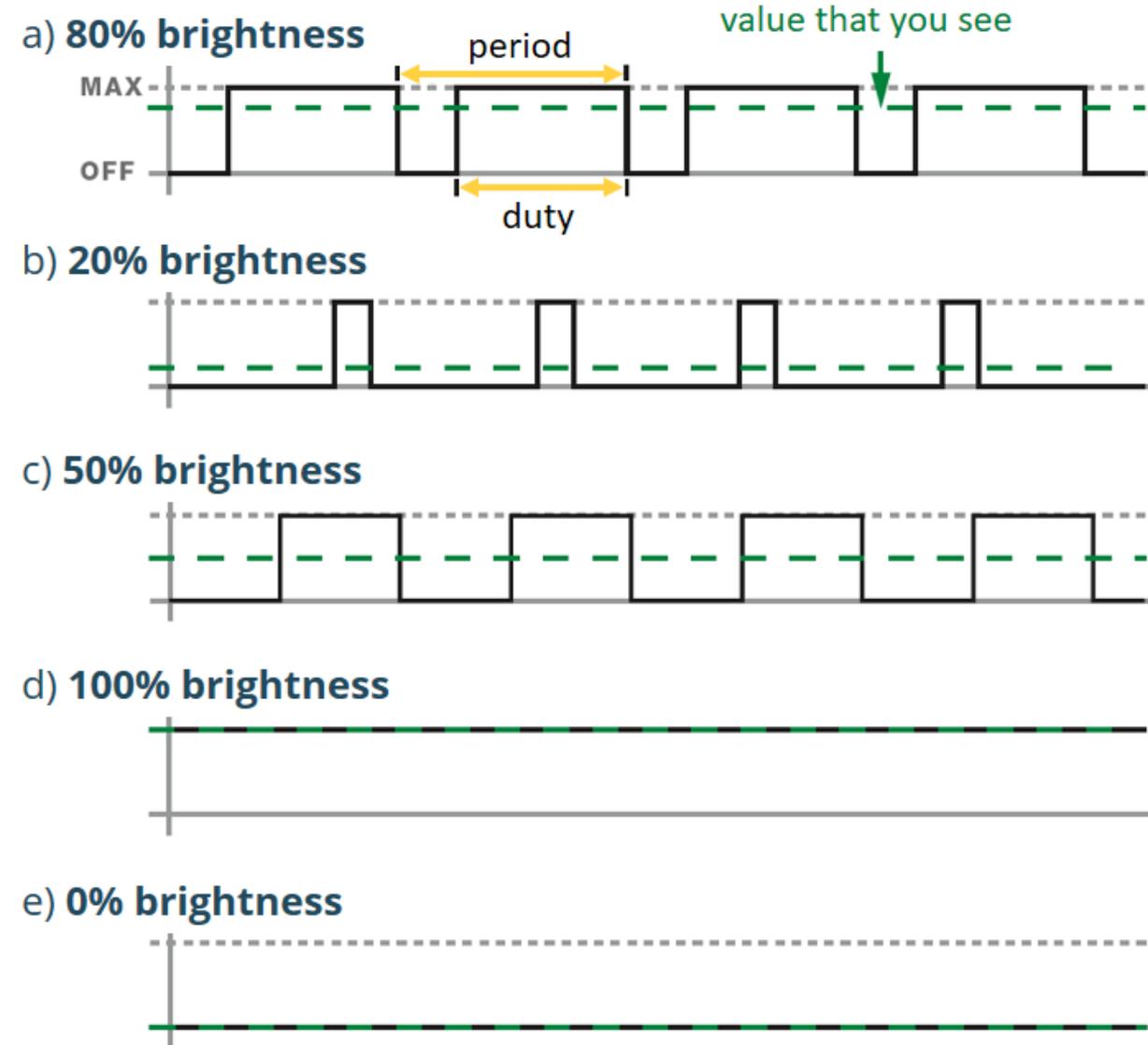
It's one of the primary means by which microcontrollers drive analog actuators such as variable-speed motors, dimmable lights, and speakers



Changing the LED Brightness using PWM

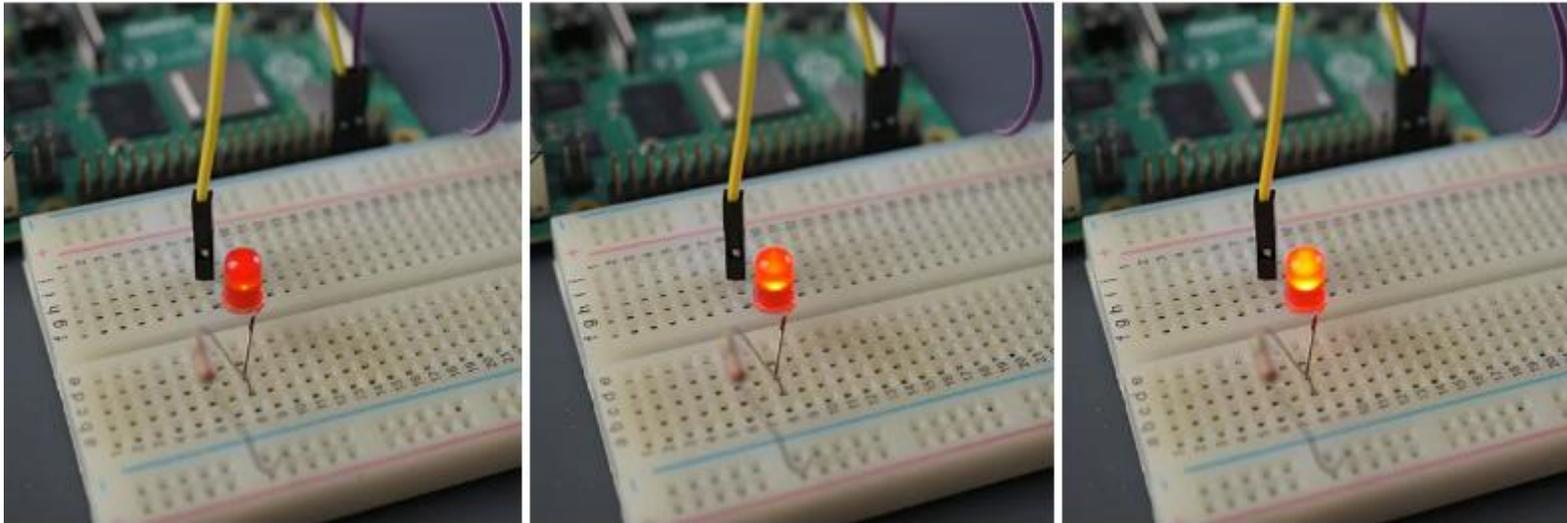
# PWM- LED Brightness

- The Raspberry Pi has 4 hardware PWM pins: GPIO 12, GPIO 13, GPIO 18, GPIO 19
- PWM works — by producing an output that changes between HIGH and LOW at a very high frequency.
- The duty cycle is the fraction of the time period at which LED is set to HIGH.
- A duty cycle of 50 percent results in 50 percent LED brightness, a duty cycle of 0 means the LED is fully off, and a duty cycle of 100 means the LED is fully on. Changing the duty cycle is how you produce different levels of brightness.



# LED With Analog Output

Build a circuit to change the LED brightness using one of the Raspberry Pi 's analog outputs.



# LED With Analog Output- Code

```
import RPi.GPIO as GPIO
import time

# Pin configuration
LED_PIN = 40 # Physical pin 40 (BOARD numbering)

# GPIO setup
GPIO.setmode(GPIO.BOARD) # Use physical pin numbering
GPIO.setup(LED_PIN, GPIO.OUT) # Set the pin as an output

# Set up PWM for the LED
pwm = GPIO.PWM(LED_PIN, 100) # 100 Hz frequency
pwm.start(0) # Start with 0% duty cycle (LED off)

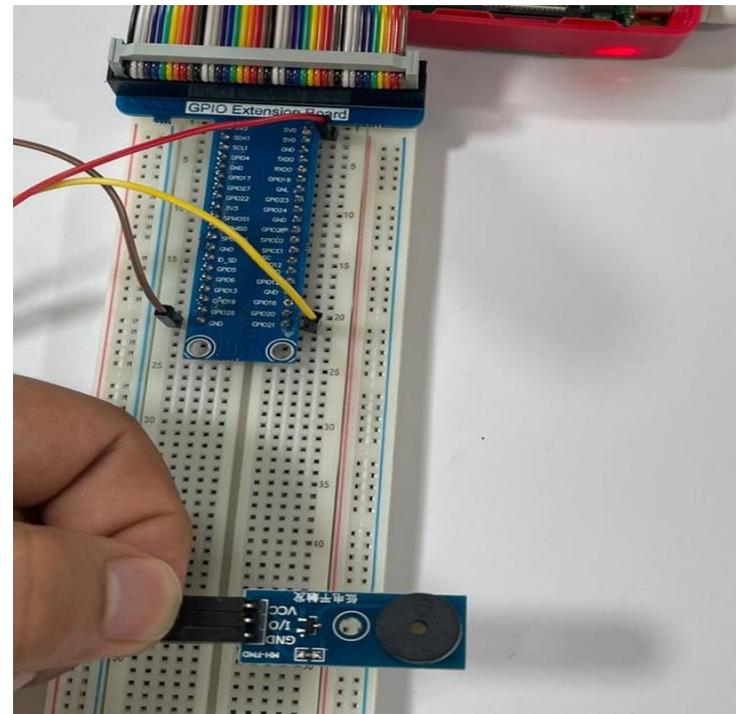
try:
    while True:
        # Gradually increase brightness
        for duty_cycle in range(0, 101, 5): # 0% to 100% in steps of 5
            pwm.ChangeDutyCycle(duty_cycle)
            time.sleep(0.5) # Small delay for smooth transition

        # Gradually decrease brightness
        for duty_cycle in range(100, -1, -5): # 100% to 0% in steps of 5
            pwm.ChangeDutyCycle(duty_cycle)
            time.sleep(0.5)

except KeyboardInterrupt:
    print("Exiting program.")
finally:
    pwm.stop() # Stop PWM
    GPIO.cleanup() # Reset GPIO settings
```

# Buzzer With Analog Output

Build a circuit to change the Buzzer tone level using one of the Raspberry Pi 's analog outputs.



# Buzzer With Analog Output- Code

```
import RPi.GPIO as GPIO
import time

# Pin configuration
BUZZER_PIN = 40 # Physical pin 40 (BOARD numbering)

# GPIO setup
GPIO.setmode(GPIO.BOARD) # Use physical pin numbering
GPIO.setup(BUZZER_PIN, GPIO.OUT) # Set the pin as an output

# Set up PWM for the buzzer
pwm = GPIO.PWM(BUZZER_PIN, 1000) # Start with 1000 Hz frequency
pwm.start(0) # Start with 0% duty cycle (buzzer off)

try:
    while True:
        # Generate tones with varying frequencies
        for freq in [262, 330, 392, 494]: # C4, E4, G4, B4 (notes)
            pwm.ChangeFrequency(freq) # Change to the desired frequency
            pwm.ChangeDutyCycle(50) # 50% duty cycle for a consistent tone
            print(f"Playing tone at {freq} Hz")
            time.sleep(1) # Play each tone for 1 second
        pwm.ChangeDutyCycle(0) # Turn off the buzzer for a pause
        time.sleep(1)
except KeyboardInterrupt:
    print("Exiting program.")
finally:
    pwm.stop() # Stop PWM
    GPIO.cleanup() # Reset GPIO settings
```

# Take-Home Task

Build a circuit that reads the intensity of light using LDR sensor then change the buzzer tone level as the following:

Completely dark: high tone level

Dark: medium tone level

Normal Light: buzzer oFF

Flashlight: low tone level